

# Getting LKF-wise dissipation to ensure ISS for Time-Delay Systems

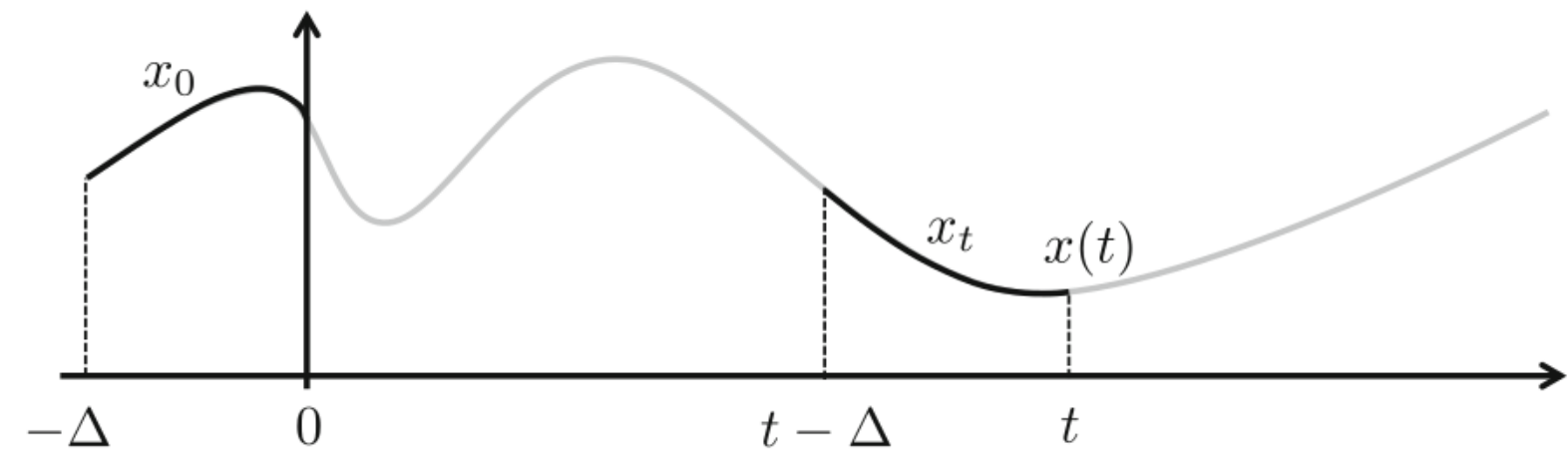
## Abstract

For time-delay systems, we want to make the Lyapunov ISS analysis like in finite dimension:  $\dot{x}(t) = f(x(t), u(t))$ .

## TIME-DELAY SYSTEMS & LKF

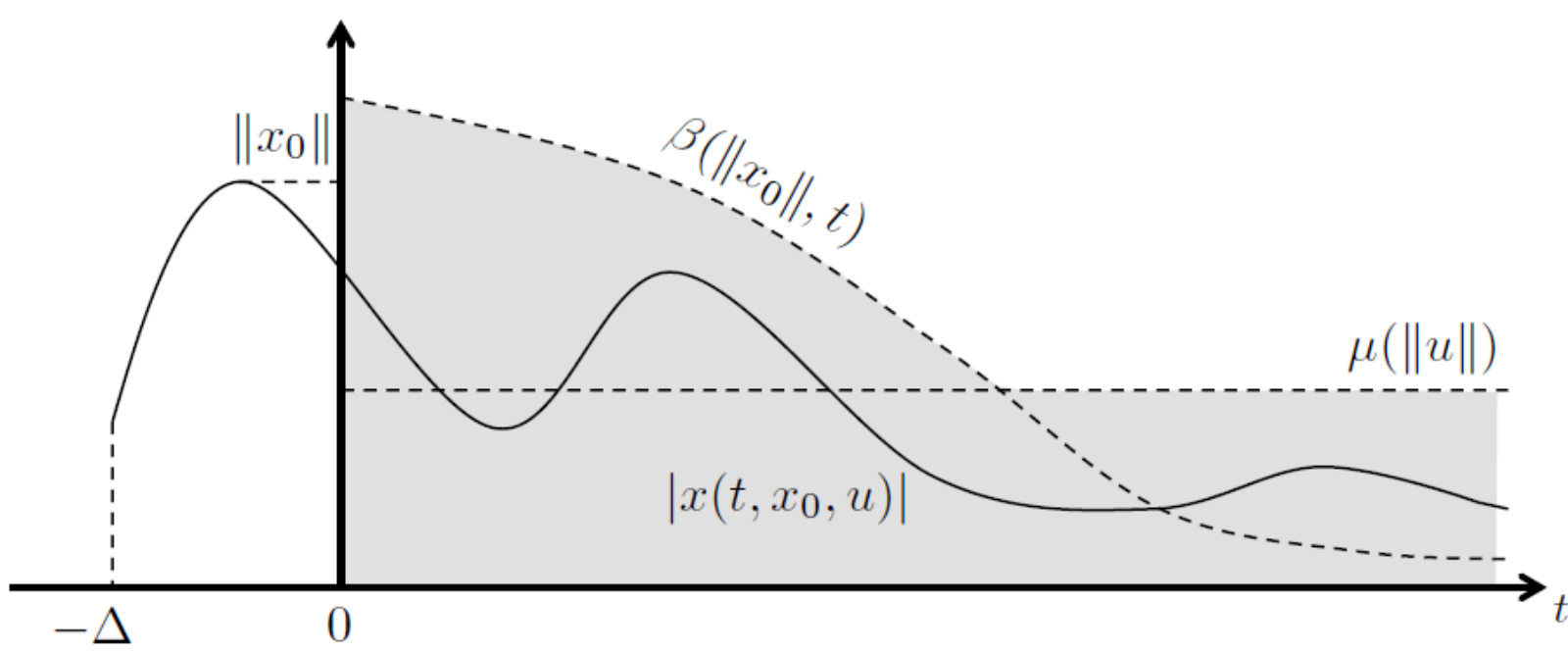
### • Time-delay systems (TDS):

$$\dot{x}(t) = f(x_t, u(t)), x_t : [-\Delta, 0] \ni s \mapsto x(t+s) \in \mathbb{R}^n.$$



### • Input-to-state stability (ISS):

$$|x(t, x_0, u)| \leq \max\{\beta(\|x_0\|, t), \mu(|u(t)|)\}; \|x_0\| = \max_{s \in [-\Delta, 0]} |x_0(s)|.$$



### • Lyapunov-Krasovskii functional (LKF): $V$ Lipschitz on bounded sets and

$$\underline{\alpha}(\|x(t)\|) \leq V(x_t) \leq \bar{\alpha}(\|x_t\|).$$

**Theorem 1** (Karafyllis et al., 2008): ISS of TDS  $\Leftrightarrow \exists$  LKF  $V$  :

$$D^+V \leq -\alpha(V(x_t)) + \gamma(|u(t)|). \quad (1)$$

↑↑↑

LKF-wise dissipation: sometimes hard to obtain

**Conjecture** (Chaillet et al., 2017) ISS of TDS  $\Leftrightarrow \exists$  LKF  $V$  with

$$D^+V \leq -\alpha(\|x(t)\|) + \gamma(|u(t)|). \quad (2)$$

↑↑↑

point-wise dissipation: easy to obtain

## POINT-WISE DISSIPATION

### The adding exponential trick

- When it works:

$$V(x_t) = w_1(x(t)) + \int_{-\Delta}^0 w_2(x_t(s)) ds. \quad (3)$$

**Proposition 1** (Loko et al., 2024b): If the LKF (3) satisfies (2) with  $w_2(z) \leq \varepsilon \alpha(|z|)$ , then

$$W(x_t) = w_1(x(t)) + \int_{-\Delta}^0 k e^{cs} w_2(x_t(s)) ds \quad (4)$$

is an ISS LKF with LKF-wise dissipation and the TDS is ISS.

- When it does not work

**Proposition 2** (Loko et al., 2024b): Consider the following 1D TDS:

$$\dot{x}(t) = -x(t) - \frac{x(t)}{1+x(t)^2} + \frac{x(t-1)^4}{1+|x(t)|^3} + \frac{u(t)}{1+x(t)^2}. \quad (5)$$

- \* The TDS (5) is ISS.
- \* The LKF  $V$  in (3) with  $w_2(z) = 4w_1(z) = z^4$  dissipates point-wisely.
- \* For any  $k, c > 0$ , the corresponding LKF  $W$  (4) does not dissipate LKF-wise.

## ISS with point-wise dissipation

**Theorem 2** (Loko et al., 2024b): Given a LKF  $V$  dissipating as

$$D^+V \leq -\alpha(Q(x(t))) + \gamma(|u(t)|)$$

with  $Q$  smooth and positive definite function. Easy to show that

$$\dot{Q}(x(t)) \leq \sigma(\|x_t\|) + \gamma(|u(t)|).$$

Then the considered TDS is ISS provided that

$$\liminf_{s \rightarrow +\infty} \alpha(s) / \sigma(se^\Delta) > 0.$$

### Example 1

$$\dot{x}(t) = -2x(t)^3 + x(t)x(t-\Delta)^2 + x(t)u(t). \quad (6)$$

- Using Theorem 2 or Proposition 1, we are able to show the ISS of TDS (6).
- Existing ISS results like in (Chaillet et al., 2023) and in (Orlowski et al., 2022) do not apply.

### Example 2

$$\begin{cases} \dot{x}_1(t) = -2x_1(t) + x_2(t-\Delta)^3 + u(t) \\ \dot{x}_2(t) = -x_2(t) - x_2(t)^9 \end{cases} \quad (7)$$

- The TDS (7) is ISS based on Theorem 2.
- ISS result in (Chaillet et al., 2017) does not apply.

## COERCIVE LKF BUILDING

**Theorem 3** (Loko et al., 2024a): For any function  $Q$  satisfying Razumikhin condition presented in (Teel, 1998) or Halanay condition presented in (Halanay, 1966), the LKF  $V$  defined as

$$V(x_t) = \max_{s \in [-\Delta, 0]} e^{cs} Q(x_t(s))$$

is a coercive LKF with LKF-wise dissipation for the considered TDS.

### Application: Chemical reactor model

$$\begin{aligned} \partial_t x_c(t, z) + c \partial_z x_c(t, z) &= -\xi x_c(t, z) + \xi x(t) \\ \dot{x}(t) &= g(x(t)) - (\mu + 1)x(t) + \mu \int_0^1 x_c(t, z) dz + u(t). \end{aligned}$$

- ISS requirement is improved for the system.
- Unlike the several existing stability analysis, we used the sup norm.

## CONCLUSION & PERSPECTIVES

- The conjecture is still an open question.
- Improve our Razumikhin and Halanay conditions.
- Look for LKF from vector version of Halanay.

## REFERENCES



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